Data Reduction: How to Make Your Own Light Curves

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Outline:

- Preliminaries
- Basic data reduction framework
- Questions

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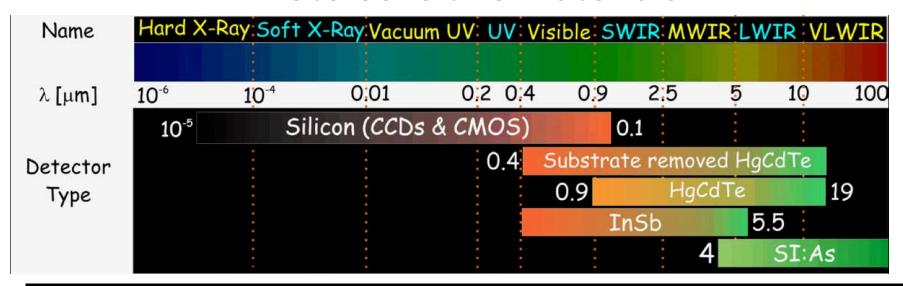
Data reduction golden rules:

- Document, document, document.
- Do the best that you can to estimate your confidence intervals.
- Be willing to not publish bad data sets.

Know your detector technology!

- What is the photo-sensitive material?
- What is the read-out circuit architecture?

Photo-sensitive materials:



Material Name	Symbol	E _g (eV)	λ _c (μm)
Silicon	Si	1.12	1.1
Indium-Gallium-Arsenide	InGaAs	0.73 – 0.48	1.68* – 2.6
Mer-Cad-Tel	HgCdTe	1.00 – 0.07	1.24 – 18
Indium Antimonide	InSb	0.23	5.5
Arsenic doped Silicon	Si:As	0.05	25

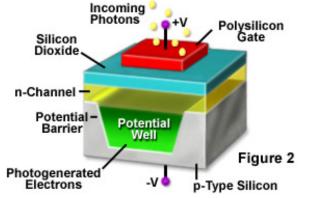
Know your detector technology!

- What is the photo-sensitive material?
- What is the read-out circuit architecture?

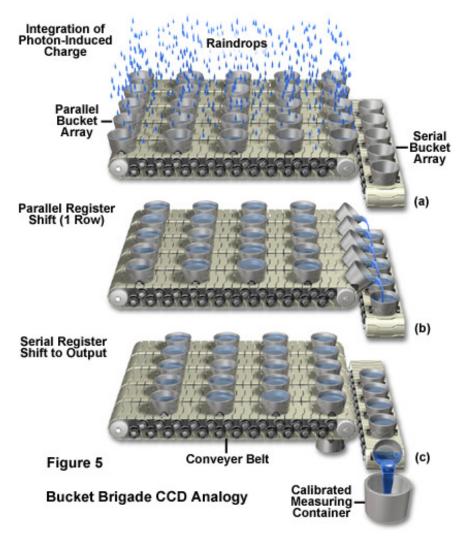
Read-out Circuit Architectures:

CCD (charge-coupled device)

Metal Oxide Semiconductor (MOS) Capacitor Incoming



- serial voltage generation
- only destructive reads



Read-out Circuit Architectures:

Hybrid CMOS (complementary metal–oxide–semiconductor)

- voltage generation at the pixel level (parallel)
- non-destructive reads
- higher read noise

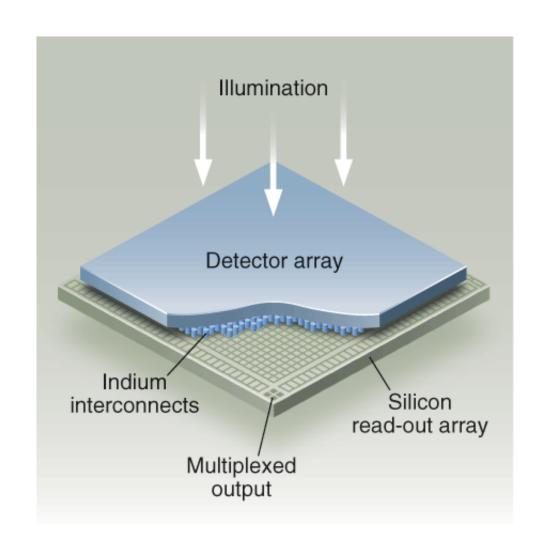


Image credit: Ian McLean

Question standard techniques!

Example: dithering/nodding for ground-based NIR observations to remove sky background

Basic terms/concepts:

"full-well" = number of free photoelectrons that a pixel can hold

Typical values on order of 100,000 electrons, range 70,000 – 200,000

IR detectors generally lower, optical detectors generally higher

Basic terms/concepts:

"gain" = electrons per data number for analog-to-digital conversion

Typical value on order of 1, range 0.5 - 5

Large values correspond to low gain, small values to high gain

Be wary of different modes that are not supported

Basic terms/concepts:

"saturation" = when output digital signal no longer responsive to more incident light

Can occur at the pixel level (full-well depth exceeded),

Or at the analog-to-digital converter (ADC saturated)

Note: ADCs are typically 16 bit devices, so are limited to $2^16 - 1 = 65535$

Saturation in CCDs leads to blooming, but flux can be conserved

Saturation in IR arrays can be mitigated with up-the-ramp sampling

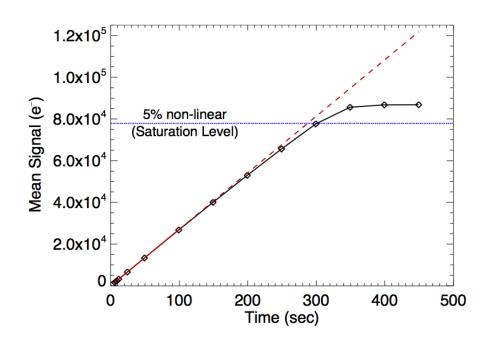
Basic terms/concepts:

"non-linearity" = deviation from a one-to-one correspondence of incident photons and generated photoelectrons

CCDs very linear up to near the saturation level (at least 50k DN)

IR detectors are strongly nonlinear.

Non-linearity can (must) be calibrated, but there is a point where the corrections break down. Typically this is well below saturation.



HST/WFC3 instrument manual for IR channel

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Goal: Measure stellar flux as a function of time (and wavelength)

Limitations:

- Noise inherent in the data =
 shot noise (star + background) + read noise + uncertainty in the processing
- Time and/or wavelength varying systematics =
 instrumental + Earth's atmosphere + stellar variability

Task: Extract maximum possible information from the data and minimize systematics

Typical steps (not a recipe):

- Remove detector systematics
- Extract flux and separate star from background
- Record diagnostics of data acquisition and reduction
- Calibrate data
- Remove light curve systematics

Estimate and propagate uncertainties at every step!

Remove detector systematics



Possible steps:

- Remove bias/pedestal
- Remove dark current
- Collapse data cubes
- Apply flat field correction
- Apply non-linear corrections

Remove detector systematics



Possible steps:

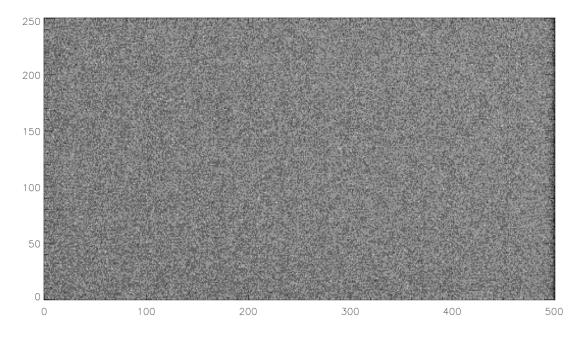
- Remove bias/pedestal → subtract bias frame
- Remove dark current
- Collapse data cubes
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Remove detector systematics



Example CCD bias frame (Gemini + GMOS)

min to max is 5 DN



Remove detector systematics



Possible steps:

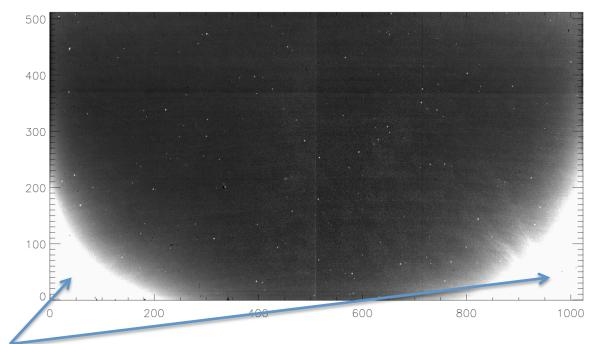
- Remove bias/pedestal → subtract bias frame
- Remove dark current → subtract dark frame
- Collapse data cubes
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Remove detector systematics



Example 300s InSb dark frame (VLT + CRIRES)





amplifier glow

Remove detector systematics



Possible steps:

- Remove bias/pedestal → subtract bias frame
- Remove dark current → subtract dark frame
- Collapse data cubes → only for IR detectors
- Apply flat field correction
- Apply non-linear corrections

Remove detector systematics

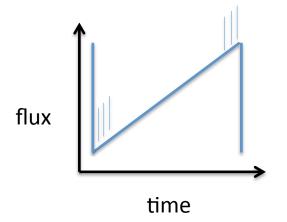


IR detector read modes

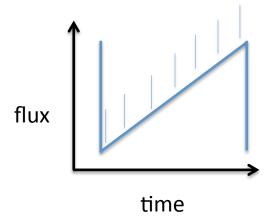
Advantages:

- Both remove variable pedestal
- Both reduce read noise
- Up-the-ramp can allow rejection of cosmic rays and use of saturated pixels

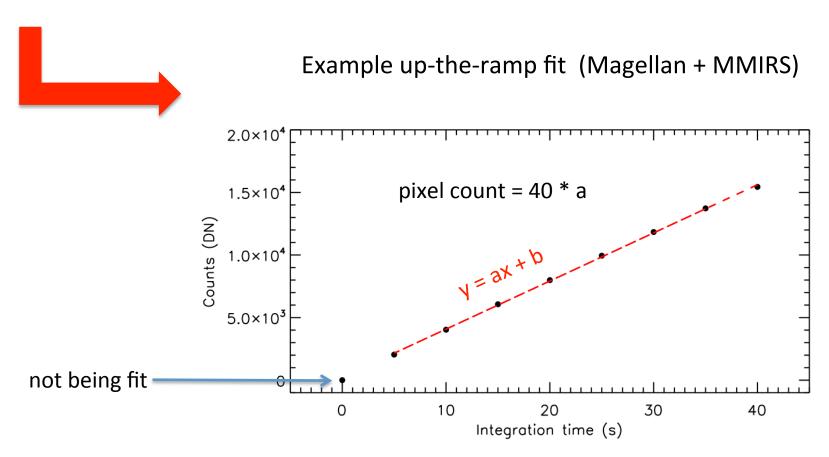
Double-correlated (Fowler) sampling



Sample up-the-ramp



Remove detector systematics



Remove detector systematics



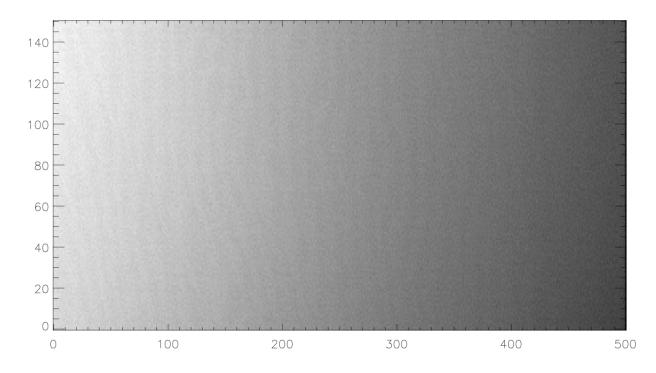
Possible steps:

- Remove bias/pedestal → subtract bias frame
- Remove dark current → subtract dark frame
- Collapse data cubes → only for IR detectors
- Apply flat field correction → divide by flat field frame
- Apply non-linear corrections

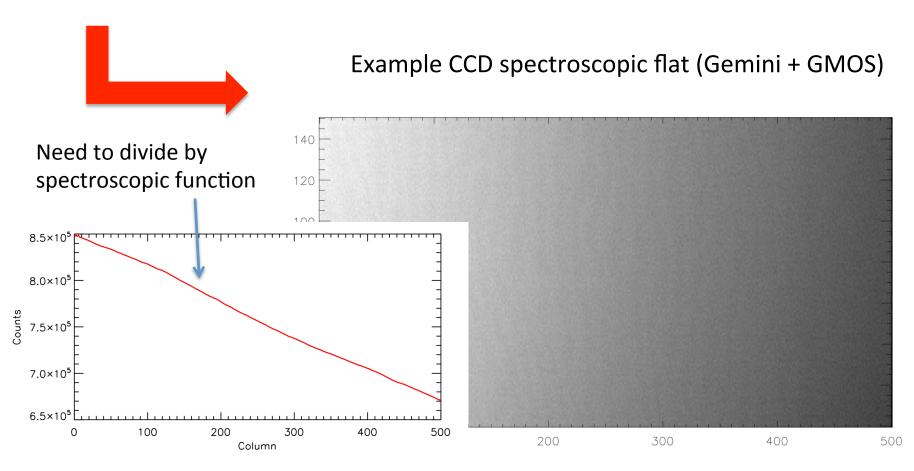
Remove detector systematics



Example CCD spectroscopic flat (Gemini + GMOS)



Remove detector systematics

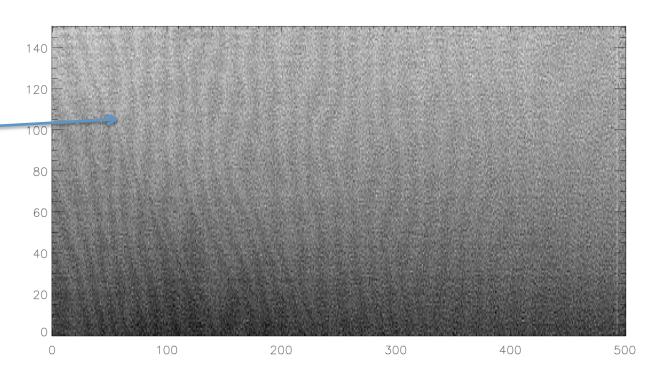


Remove detector systematics

Example CCD spectroscopic flat (Gemini + GMOS)

Fringing from internal reflections inside detector at wavelengths approaching silicon bandgap

variations are ± 5%



Remove detector systematics



Possible steps:

- Remove bias/pedestal → subtract bias frame
- Remove dark current → subtract dark frame
- Collapse data cubes → only for IR detectors
- Apply flat field correction → divide by flat field frame
- Apply non-linear corrections → based on calibration data

Typical steps (not a recipe):

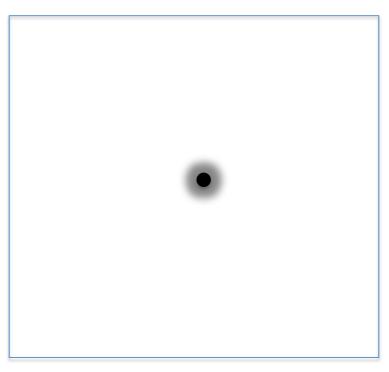
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Estimate and propagate uncertainties at every step!

Extract flux and separate star from background



Imaging = aperture photometry

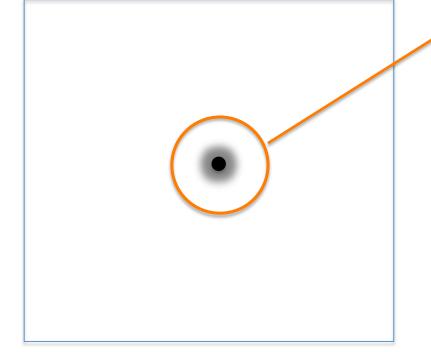


Many standard routines for this in IRAF, IDL, and probably Python, etc too.

Extract flux and separate star from background



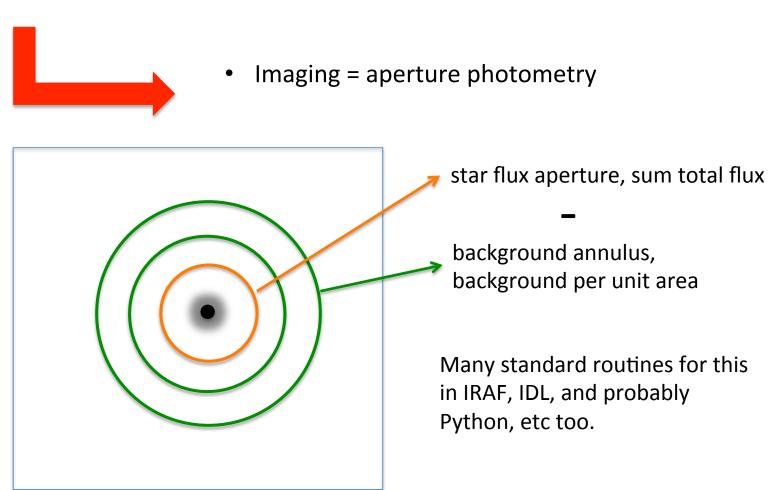
Imaging = aperture photometry



star flux aperture, sum total flux

Many standard routines for this in IRAF, IDL, and probably Python, etc too.

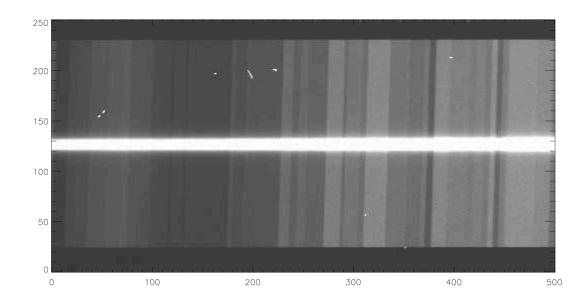
Extract flux and separate star from background



Extract flux and separate star from background



- Imaging = aperture photometry
- Spectroscopy = spectrum extraction

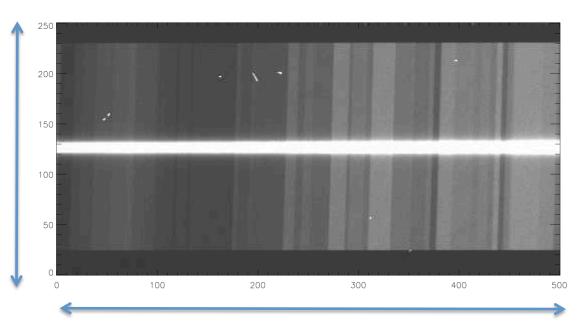


Extract flux and separate star from background



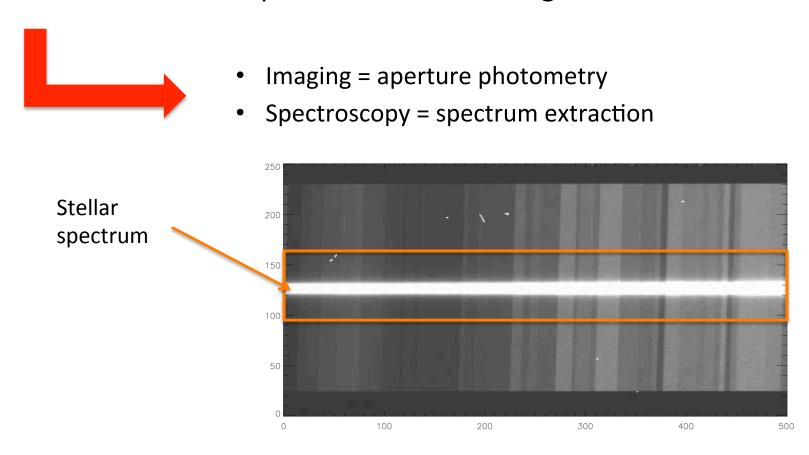
- Imaging = aperture photometry
- Spectroscopy = spectrum extraction

"spatial" direction

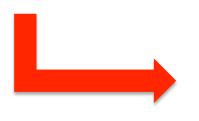


"dispersion" direction

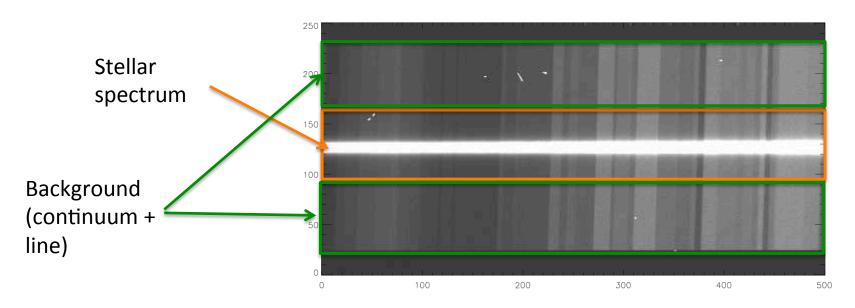
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Extract flux and separate star from background



- Imaging = aperture photometry
- Spectroscopy = spectrum extraction

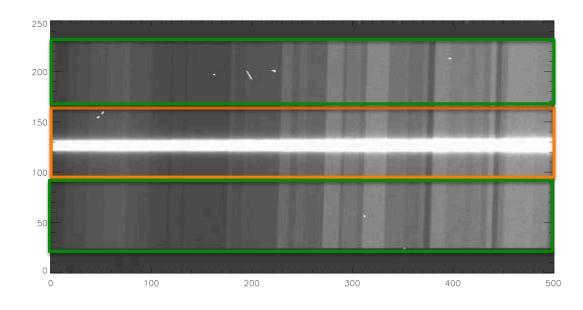


Extract flux and separate star from background



- Imaging = aperture photometry
- Spectroscopy = spectrum extraction

Step 1: Estimate background as a function of wavelength (note slit tilt/curvature)



Extract flux and separate star from background

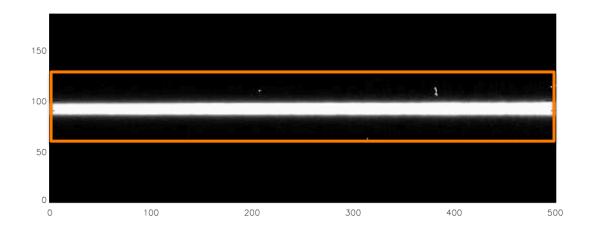


- Imaging = aperture photometry
- Spectroscopy = spectrum extraction

Step 2: Extract spectrum

Two options:

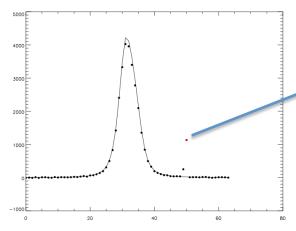
- "box" extraction = sum up the pixels
- "optimal" extraction (Horne 1986)



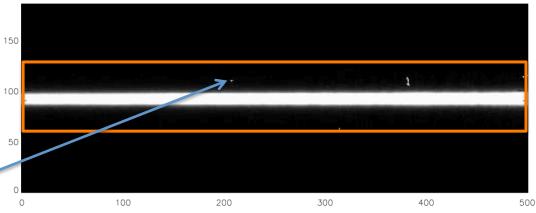
Extract flux and separate star from background



Optimal extraction:
Use estimate of spatial profile to identify and mask cosmic rays, and to weight the extraction.



- Imaging = aperture photometry
- Spectroscopy = spectrum extraction



Some freely available routines, but none that are particularly good.

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- Calibrate data
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Record diagnostics of data acquisition and reduction

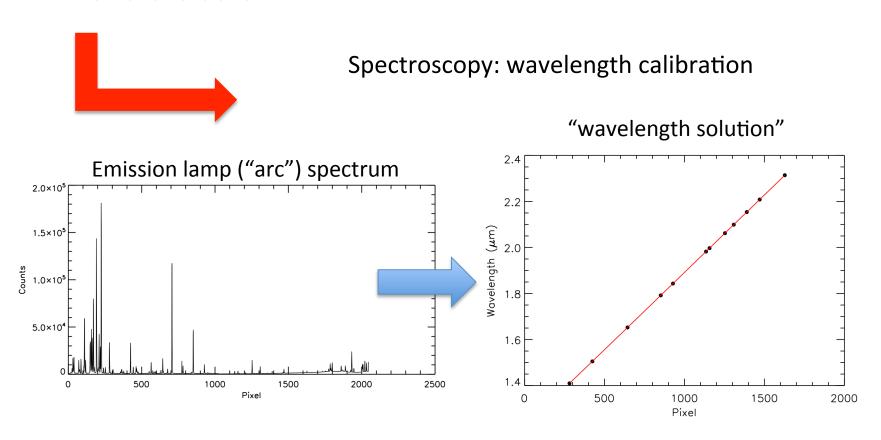


- Atmospheric conditions: airmass, water vapor, etc.
- Instrument state: detector temperature, orbital phase, focus and filter wheel position, rotator angle, etc.
- Position and width of image/spectrum
- Background flux

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Calibrate data



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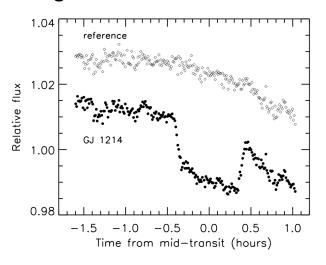
Remove light curve systematics



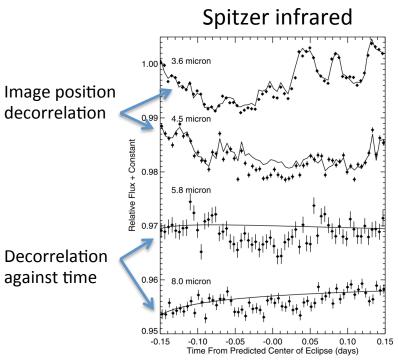
(simultaneous with light curve fitting!)

Division by reference flux and/or decorrelation function

ground-based near-infrared



Bean et al. 2011



Knutson et al. 2008

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