

Planning hybrid follow-up strategies for turning microlenses into cold worlds

Markus Hundertmark & the RoboNet team

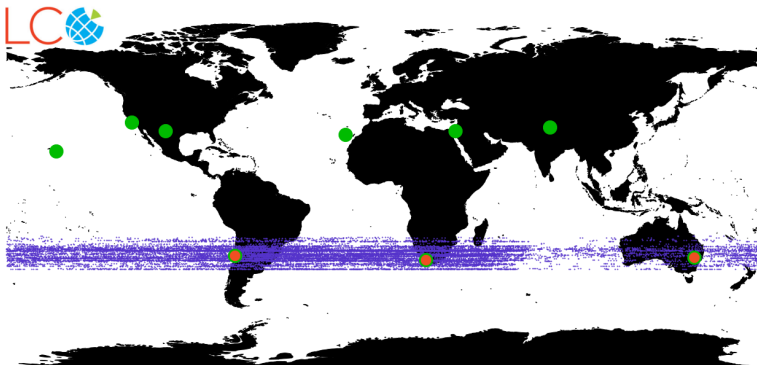
Zentrum für Astronomie der Universität Heidelberg,
Astronomisches Rechen-Institut

February 1, 2017



**UNIVERSITÄT
HEIDELBERG**
ZUKUNFT
SEIT 1386

LCO global network

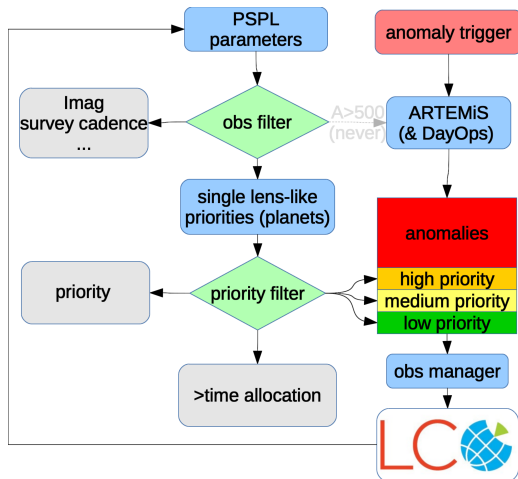


- Key project “Exploring Cool Planets Beyond the Snowline”¹
- Regular operations: 2014-2016, pilot phase 2013

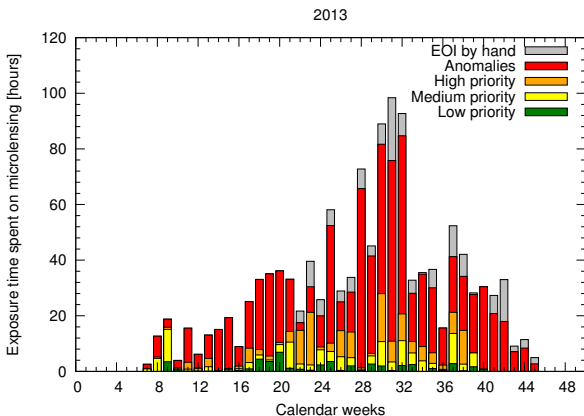
¹PI: R. Street

Underlying philosophy

- Easy operations first
- Analytic expressions
- Interpolants where appropriate
- Keep results in memory

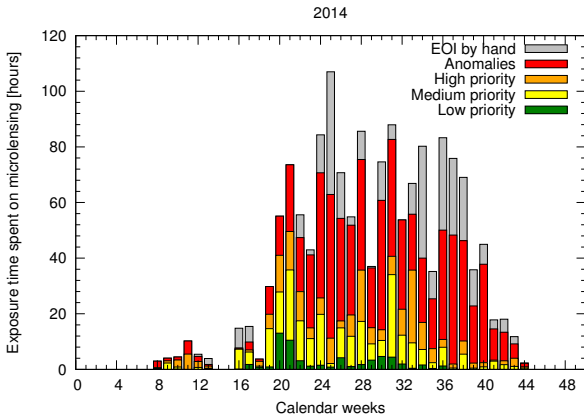


TAP in action - pilot phase



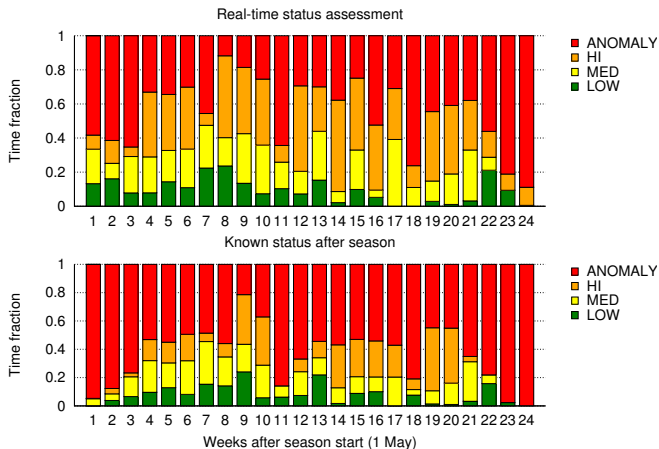
- Pilot phase (observation manager scheduled events)
- EOI: evens of interest (external requests)

TAP in action - regular operations



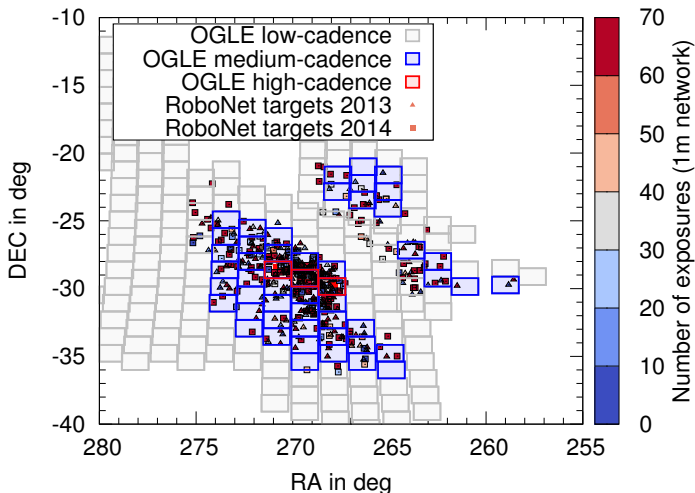
- LCO scheduler active since May 1st
- Anomalies: daily operations interaction (cadence, exptime)

Real-time and post-season status (2013)



- $\sim 10\%$ of all regular events turn out to be anomalous (mostly in high-cadence fields)

Requested targets and achieved cadence



- Precedence was given to low-cadence observations

What limits our ability to characterise planets?

Planet mass estimates

$$M_p = \frac{\mu t_E}{\kappa \pi_E} \frac{q}{1+q}; \kappa \approx 8.14 \frac{\text{mas}}{M_\odot}$$

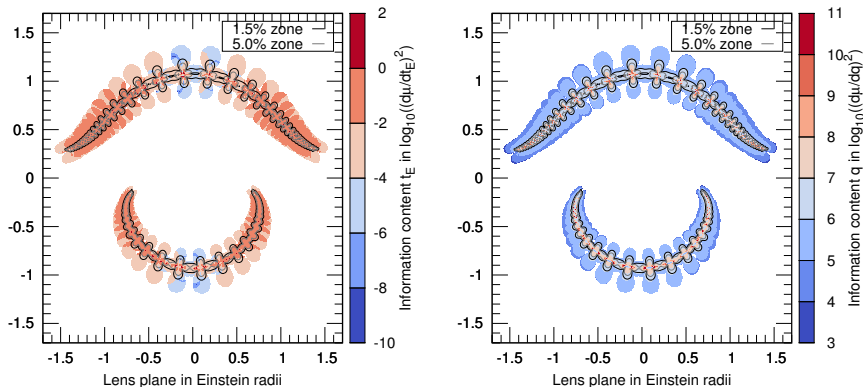
Planet mass uncertainties

$$\sigma_{M_p} = \frac{\mu q t_E}{\kappa \pi_E (1+q)} \left(\frac{\sigma_{\pi_E}^2}{\pi_E^2} + \frac{\sigma_\mu^2}{\mu^2} + \frac{\sigma_q^2}{q^2 (1+q)} + \frac{\sigma_{t_E}^2}{t_E^2} \right)^{1/2}$$

⇒ The term with maximum relative uncertainty limits us.

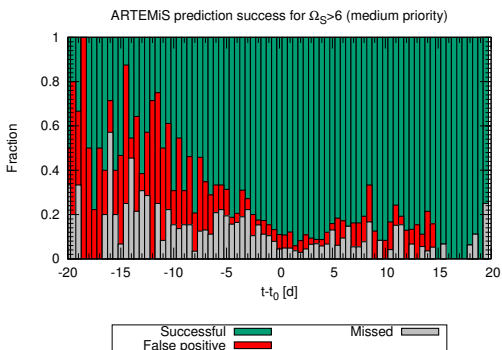
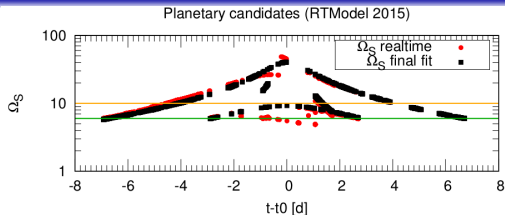
Detection zones contribute to characterisation

Information content for t_E and mass ratio q in a $u_0 = 0.15$ event



- Planet perturbation coincides with sensitivity in q
- Rule of thumb: 10-15 points sufficient for characterization

False-positives and priority function

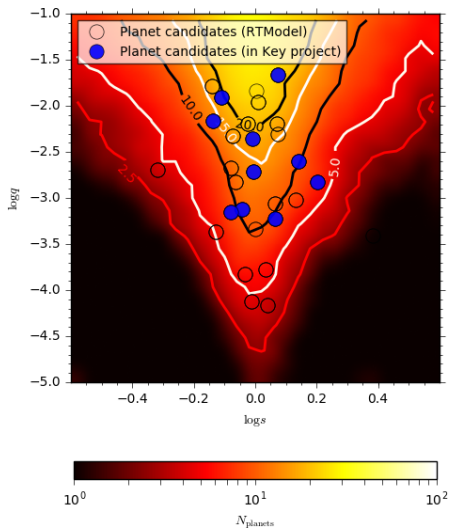


- Priority Ω_S : Planet probability per invested time
- Thresholds based on full-season simulation^a
- Fractions of over- and underrated events
- How early can we obtain a reasonable estimate?

^aDominik et al. 2010

RoboNet sensitivity 2013 & 2014

- Non-anomalous events: 181
- Peak sensitivity 20%
- 1/2 candidates from anomaly monitoring
- > 1 planet per year
- Candidates from RTModel (Bozza 2010)

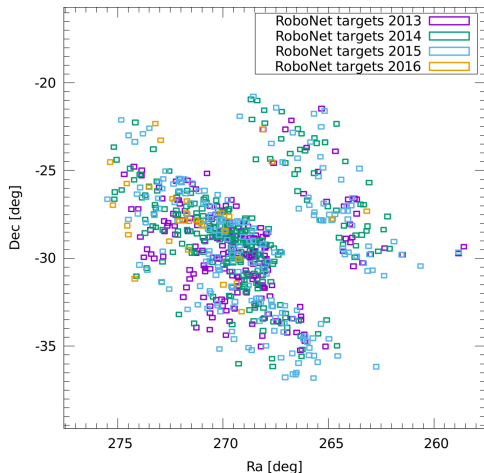


Remarks on the sensitivity estimates

- Mass function: requires number of detections, campaign sensitivity & corresponding uncertainties
- Even for $\log q$: Galactic model and t_E rejection of brown dwarfs and free-floating planets
- “Single star mass(-ratio) function”: Detected binaries 2-3 % (Tsapras et al. 2016), actually 20-30 %
- Blending: correlated with t_E , thus relevant for mass function estimates

For an independent study: baseline

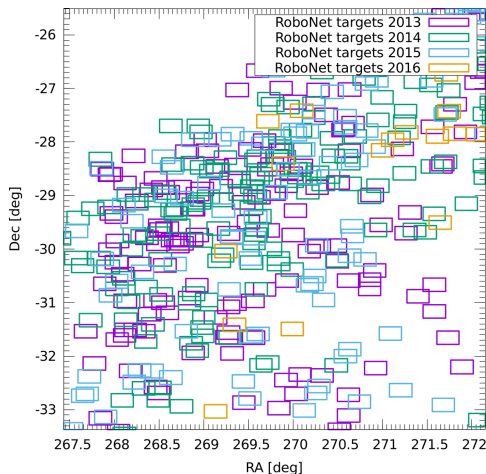
- Event centered follow-up does not guarantee baseline coverage
- > 700 events ($15' \times 15'$) in 4 years
- Data-mining opportunity for the future



Camera footprint

For an independent study: baseline

- Event centered follow-up does not guarantee baseline coverage
- > 700 events ($15' \times 15'$) in 4 years
- Data-mining opportunity for the future



Camera footprint

Conclusions

- Hybrid strategies increase the chance to cover planetary events (5 planet candidates per year for LCO Key project)
- Human-interaction was limited to anomalies and their cadence
- Initial two-years were optimized for targets within the OGLE footprint
- Insights from 2015: more sensitivity has not lead to more detections

Thank you to all teams supporting our efforts!