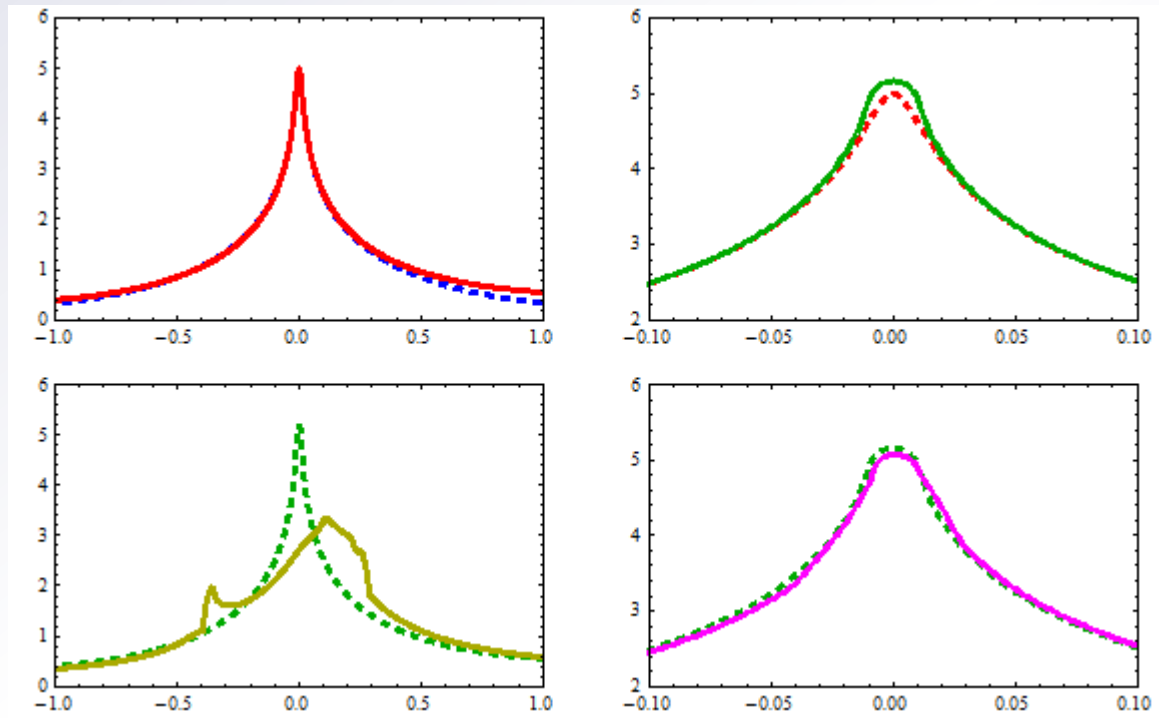


# VBBinaryLensing

A public code for binary microlensing computation



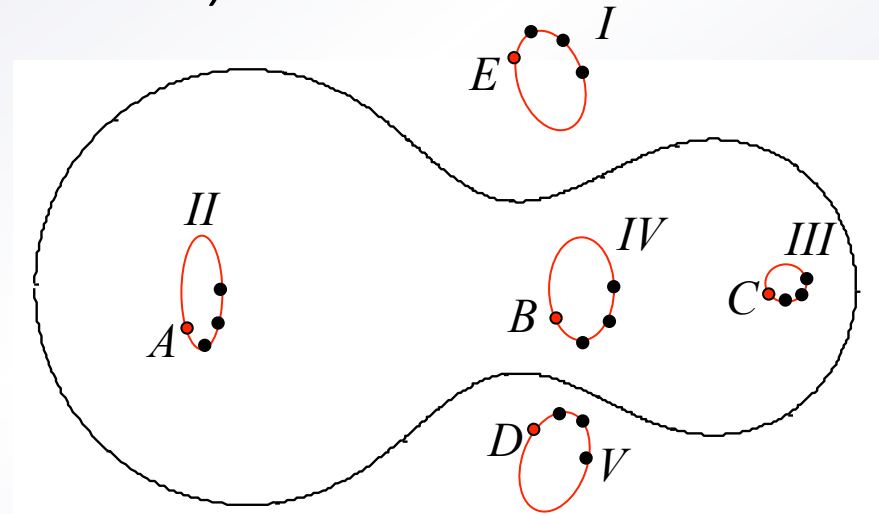
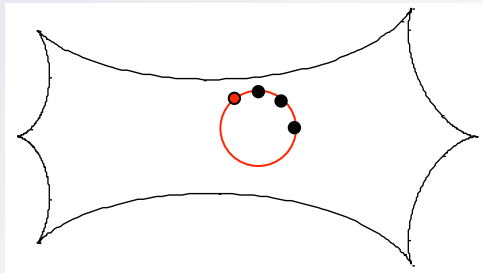
Valerio Bozza  
University of Salerno, Italy

# What is VBBinaryLensing

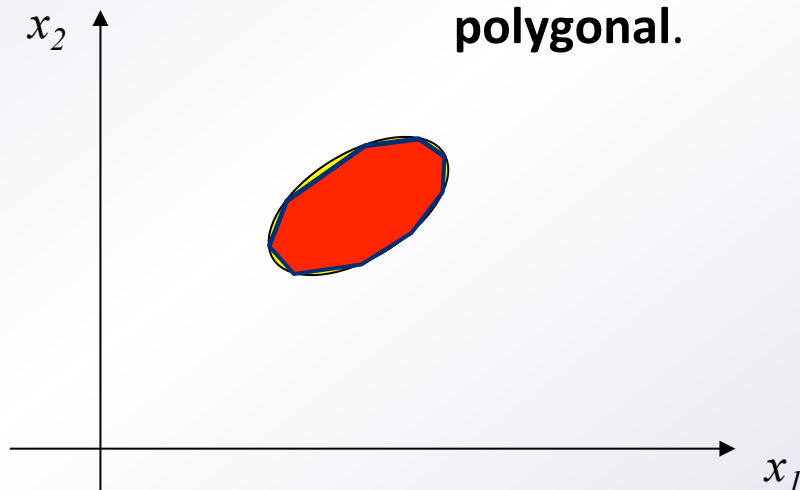
- **VBBinaryLensing** is a code for the calculation of **microlensing light curves**.
  - Point-Source Point-Lens
  - Extended Source Point-Lens
  - Binary Source Point-Lens
  - Extended Source Binary Lens
- **Higher order effects** implemented:
  - Linear limb darkening
  - Annual and space parallax
  - Circular orbital motion
- C++ library.
- Tested on Windows, Linux, Mac OS.
- Importable in Python.
- Source code is public (but no specific standard has been adopted!).

# Magnification in Binary Lensing

- Magnification by binary lenses is calculated with the **contour integration** method (*Schramm & Kayser 1987; Dominik 1993; Dominik 1995; Gould & Gaucherel 1997; Dominik 1998; Dong et al. 2006; Dominik 2007*).



- Area traditionally estimated by a **polygonal**.



- Area is typically underestimated.
- Uniform sampling is insufficient and/or inefficient.
- Ambiguities in case of source crossing a caustic.
- No limb darkening.

# Advanced Contour Integration

(Bozza, MNRAS 408, 2188 (2010))

## Parabolic correction:

- The simple trapezium formula can be corrected by a third order term:

$$A = \sum_{i=0}^{n-1} \frac{1}{2} \mathbf{x}_I(\theta_i) \wedge \mathbf{x}_I(\theta_i + \Delta\theta) + \frac{1}{24} \left[ (\mathbf{x}'_I \wedge \mathbf{x}''_I) \Big|_{\theta_i} + (\mathbf{x}'_I \wedge \mathbf{x}''_I) \Big|_{\theta_i + \Delta\theta} \right] \Delta\theta^3 + O(\Delta\theta^5)$$

- The same accuracy can be reached with much fewer sampling points, saving computational time.

## Error control:

- For each boundary arc we can estimate the error in our approximation with three indicators working in complementary ways:

$$E_{I,i,1} = \frac{1}{48} \left| (\mathbf{x}'_I \wedge \mathbf{x}''_I) \Big|_{\theta_i} - (\mathbf{x}'_I \wedge \mathbf{x}''_I) \Big|_{\theta_i + \Delta\theta} \right| \Delta\theta^3$$

$$E_{I,i,2} = \frac{3}{2} \left| \Delta A_I^{(p)} \left( \frac{\Delta\tilde{\theta}^2}{\Delta\theta^2} - 1 \right) \right|$$

$$E_{I,i,3} = \frac{1}{10} \left| \Delta A_I^{(p)} \right| \Delta\theta^2$$

- The total error in the magnification is

$$E = \sum_{i=0}^{n-1} \sum_I \sum_{k=1}^3 E_{I,i,k}$$

- The target accuracy  $\delta\mu$  is reached if

$$\frac{E}{\pi\rho_*^2} < \delta\mu$$

# Advanced Contour Integration

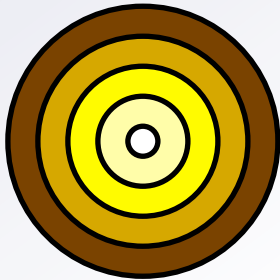
(Bozza, *MNRAS* 408, 2188 (2010))

## Optimal sampling:

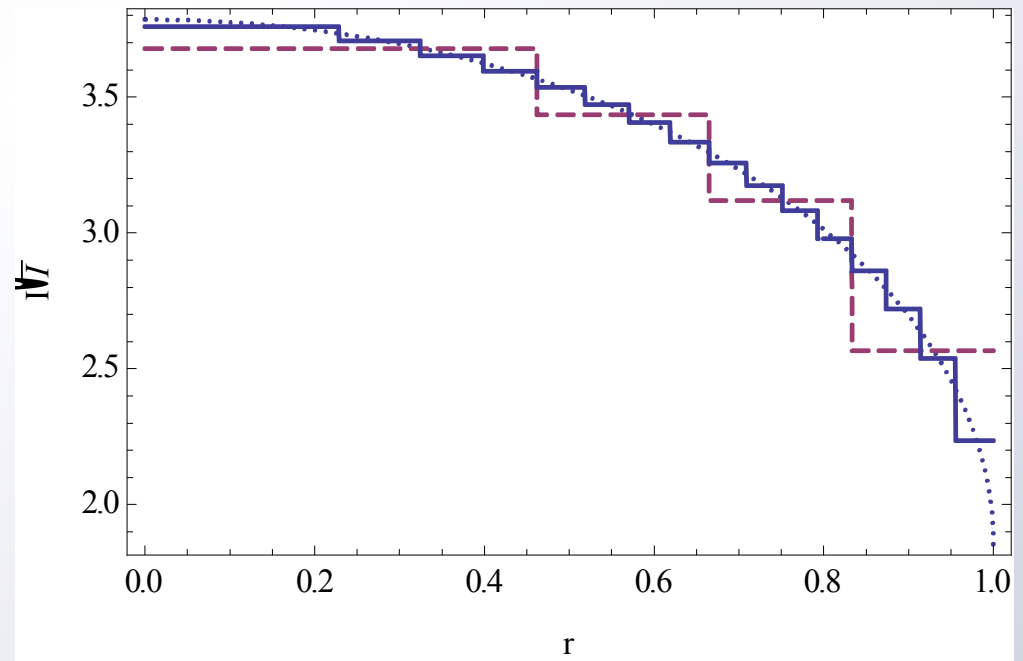
- We increase the sampling where the error is largest (optimal sampling).
- We stop when the target accuracy is reached.

## Limb darkening:

- In contour integration, limb darkening can be taken into account by calculating the magnification in concentric annuli and weighing them by the brightness profile.



- We sample uniformly in the integrated flux rather than radius.
- We use estimators for the residual error and thus **introduce optimal sampling**.



# Testing Advanced contour integration

- Advanced contour integration is at the core of **RTModel**, the real-time modelling platform at Salerno University (<http://www.fisica.unisa.it/GravitationAstrophysics/RTModel.htm>).
- It has thus been extensively **tested in 5 years of real-time modelling** with any kind of binary events.
- It has been used in the **analysis of two specific events**:
  - OGLE-2008-BLG-510: first automated real-time detection of a weak microlensing anomaly - brown dwarf or stellar binary, Bozza et al. (2012)*
  - Spitzer Observations of OGLE-2015-BLG-1212 Reveal a New Path toward Breaking Strong Microlens Degeneracies, Bozza et al. (2016)*
- More testing has come in the last few months after the public release of VBBinaryLensing.

# Release of VBBinaryLensing

- **VBBinaryLensing** is available at <http://www.fisica.unisa.it/GravitationAstrophysics/VBBinaryLensing.htm>.
- The **zip file** contains:
  - `readmeVB.txt` Generic introductory information
  - `VBBinaryLensingLibrary.h` C++ header
  - `VBBinaryLensingLibrary.cpp` C++ source
  - `main.cpp` Sample code with examples and instructions.
  - `Makefile.dat` Example of a makefile (courtesy of Zhu)
  - `howtopython.txt` Instructions for wrapping the library in Python code (courtesy of Hundertmark)
  - `OB151212coords.txt` Sample coordinate file for an event (used in the examples in `main.cpp`)
  - `satellite1.txt` Table for the positions of a satellite for space parallax calculation (Spitzer)
  - `satellite2.txt` Same for Kepler.

# Example of use

```
#include <stdio.h>
#include "VBinaryLensingLibrary.h"

int main()
{
    VBinaryLensing VBBL;

    double Mag,s,q,y1,y2,Rs,accuracy;
    s=0.8; //separation
    q=0.1; // mass ratio
    y1=0.01; // source position
    y2=0.3;
    Rs=0.01; // source radius

    accuracy=1.e-2; // Required accuracy of the result
    Mag=VBBL.BinaryMag(s,q,y1,y2,Rs,accuracy);

    printf("Magnification = %lf\n",Mag);

    return 0;
}
```



# Methods

```
class VBBinaryLensing
{ ...
    public:
        double BinaryMag (...);
        double BinaryMagDark (...);

        void SetObjectCoordinates (char *, char *);

        double PSPLCurve (double *, double);
        double PSPLParallaxCurve (double *, double);
        double ESPLCurve (double *, double);
        double ESPLParallaxCurve (double *, double);

        double BinaryLightCurve (double *, double);
        double BinaryLightCurveParallax (double *, double);
        double BinaryLightCurveOrbital (double *, double);
        double BinSourceMag (double *, double);
        double BinSourceParallaxMag (double *, double);
        double BinSourceXallarapMag (double *, double);
}
```

# Parallax and orbital motion

- **Parallax** is specified by two components of the parallax vector  $\pi_1, \pi_2$ .
- Two possible **reference frames** are implemented:
  - Earth acceleration and its perpendicular direction.
  - North-East direction. (just set `VBBL.parallaxsystem=1;` )
- Parallax is calculated using the JPL calculator  
[http://ssd.jpl.nasa.gov/txt/aprx\\_pos\\_planets.pdf](http://ssd.jpl.nasa.gov/txt/aprx_pos_planets.pdf).
- The magnification as seen from a **spacecraft** is obtained by setting `VBBL.satellite=1;` // or 2 or 3 if you have more than one
- Satellite ephemeris tables are accepted in the NASA Horizons format.

- Circular **orbital motion** is implemented.

- Parameters are

$$\omega_1 \equiv \frac{1}{s} \frac{ds}{dt}, \quad \omega_2 \equiv \frac{d\alpha}{dt}, \quad \omega_3 \equiv \frac{1}{s} \frac{ds_z}{dt}$$

- All other quantities can be derived from these:

$$\omega = \sqrt{\omega_1^2 + \omega_2^2 + \omega_3^2} \frac{\omega_3}{\sqrt{\omega_1^2 + \omega_3^2}}; \quad \cos i = \frac{\omega_2}{\sqrt{\omega_1^2 + \omega_2^2 + \omega_3^2}} \frac{\omega_3}{\sqrt{\omega_1^2 + \omega_3^2}}$$

# Conclusions and perspectives

- VBinaryLensing is a new **public library** for the calculation of microlensing light curves.
- It is much **faster** than any other contour integration codes thanks to its advanced tricks.
- It has a very reliable **accuracy control**.
- It comes with **many functions** already implementing **higher order effects**.
- In general, inverse ray shooting codes are advantaged for large sources, while contour integration works better for smaller sources.
- Continuous **feedback from users** since the first release has widened the testing, thus increasing the reliability of the code.
- Many suggestions from the community have already been incorporated.



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